

# ST75C176

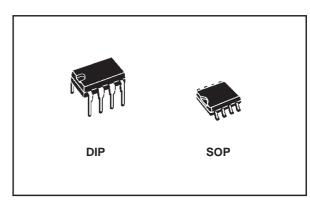
# LOW POWER RS-485/RS-422 TRANSCEIVER

- LOW QUIESCENT CURRENT: 300µA
- DESIGNED FOR RS-485 INTERFACE APPLICATIONS
- -7V TO 12V COMMON MODE INPUT VOLTAGE RANGE
- DRIVER MAINTAINS HIGH IMPEDANCE IN 3-STATE OR WITH THE POWER OFF
- 70mV TYPICAL INPUT HYSTERESIS
- 30ns PROPAGATION DELAYS, 5ns SKEW
- OPERATE FROM A SINGLE 5V SUPPLY
- CURRENT LIMITING AND THERMAL SHUTDOWN FOR DRIVER OVERLOAD PROTECTION
- ALLOWS UP TO 32 TRANSCEIVERS ON THE BUS
- BIC MOS TECHNOLOGY

#### **DESCRIPTION**

The ST75C176 is al low power transceiver for RS-485 and RS-422 communication. Each part contains one driver and one receiver.

This transceiver draw  $300\mu A$  (typ.) of supply current when unloaded or fully loaded with disabled drivers.



It operates from a single 5V supply.

Driver is short-circuit current limited and is protected against excessive power dissipation by thermal shutdown circuitry that placed the driver outputs into a high-impedance state. The receiver input has a fail safe feature that guarantees a logic-high output if the input is open circuit.

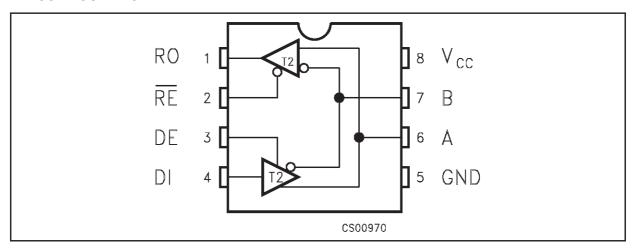
The ST75C176 is designed for bi-directional data communications on multipoint bus transmission line (half-duplex applications).

#### **ORDERING CODES**

Туре	Temperature Range	Package Comments	
ST75C176CN	0 to 70 °C	DIP-8	50parts per tube / 40tube per box
ST75C176BN	-40 to 85 °C	DIP-8	50parts per tube / 40tube per box
ST75C176CD	0 to 70 °C	SO-8 (Tube)	100parts per tube / 20tube per box
ST75C176BD	-40 to 85 °C	SO-8 (Tube)	100parts per tube / 20tube per box
ST75C176CDR	0 to 70 °C	SO-8 (Tape & Reel)	2500 parts per reel
ST75C176BDR	-40 to 85 °C	SO-8 (Tape & Reel)	2500 parts per reel

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#### **PIN CONFIGURATION**



#### **PIN DESCRIPTION**

PIN N°	SYMBOL	NAME AND FUNCTION		
1	RO	Receiver Output		
2	RE	Receiver Output Enable		
3	DE	Driver Output Enable		
4	DI	Driver Input		
5	GND	Ground		
6	A	Non-inverting Receiver Input and Non-inverting Driver Output		
7	В	Inverting Receiver Input and Inverting Driver Output		
8	V <sub>CC</sub>	Supply Voltage		

## **TRUTH TABLE (DRIVER)**

INPUTS			OUTPUTS		
RE	DE	В	Α		
Х	Н	Н	L	Н	
Х	Н	L	Н	L	
Х	L	Х	Z	Z	

X= Don't Care; Z=High Impedance

## TRUTH TABLE (RECEIVER)

	OUTPUT		
RE	DE	A-B	RO
L	L	≥ +0.2V	Н
L	L	≤ <b>-</b> 0.2V	L
Ĺ	L	INPUTS OPEN	Н
Н	L	X	Z

X= Don't Care; Z=High Impedance

#### **ABSOLUTE MAXIMUM RATINGS**

Symbol	Parameter	Value	Unit
V <sub>CC</sub>	Supply Voltage	12	V
V <sub>I</sub>	Control Input Voltage (RE, DE)	-0.5 to (V <sub>CC</sub> + 0.5)	V
V <sub>DI</sub>	Driver Input Voltage (DI)	-0.5 to (V <sub>CC</sub> + 0.5)	V
V <sub>DO</sub>	Driver Output Voltage (A, B)	± 14	V
V <sub>RI</sub>	Receiver Input Voltage (A, B)	± 14	V
V <sub>RO</sub>	Receiver Output Voltage (RO)	-0.5 to (V <sub>CC</sub> + 0.5)	V

Absolute Maximum Ratings are those values beyond which damage to the device may occur. Functional operation under these condition is not implied.

#### DC ELECTRICAL CHARACTERISTICS

(V<sub>CC</sub> = 5V  $\pm$  5%, T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub> , unless otherwise specified. Typical values are referred to T<sub>A</sub> = 25°C) (See Note 1)

Symbol	Parameter	Test Conditions	Min.	Тур.	Max.	Unit
V <sub>OD1</sub>	Differential Driver Output (No Load)				5	V
V <sub>OD2</sub>	Differential Driver Output (With Load)	$R_L = 27\Omega (RS-485) (See Fig. 1)$ $R_L = 50\Omega (RS-422) (See Fig. 1)$	1.5		5 5	V V
ΔV <sub>OD</sub>	Change in Magnitude of Driver Differential Output Voltage for Complementary Output States	$R_L = 27\Omega$ or $50\Omega$ (See Fig. 1)			0.2	V
V <sub>OC</sub>	Driver Common-Mode Output Voltage	$R_L = 27\Omega \text{ or } 50\Omega \text{ (See Fig. 1)}$			3	V
ΔV <sub>OC</sub>	Change in Magnitude of Driver Common-Mode Output Voltage for Complementary Output States	$R_L = 27\Omega$ or $50\Omega$ (See Fig. 1)			0.2	V
V <sub>IH</sub>	Input High Voltage	RE, DE, DI	2.0			V
V <sub>IL</sub>	Input Low Voltage	RE, DE, DI			0.8	V
I <sub>IN1</sub>	Input Current	RE, DE, DI			±2	μΑ
I <sub>IN2</sub>	Input Current (A, B)	$V_{CM} = 0V \text{ or } 5.25V$ $V_{DE} = 0V$ $V_{IN} = 12V$ $V_{IN} = -7V$			1 -0.8	mA mA
V <sub>TH</sub>	Receiver Differential Threshold Voltage	V <sub>CM</sub> = -7 to 12V	-0.2		0.2	V
$\Delta V_{TH}$	Receiver Input Hysteresis	$V_{CM} = 0V$		70		mV
V <sub>OH</sub>	Receiver Output High Voltage	$I_O = -4mA$ $V_{ID} = 200mV$	3.5			V
V <sub>OL</sub>	Receiver Output Low Voltage	$I_O = 4mA$ $V_{ID} = -200mV$			0.4	V
I <sub>OZR</sub>	3-State (High Impedance) Output Current at Receiver	$V_0 = 0.4 \text{ to } 2.4 \text{V}$			± 1	μΑ
R <sub>IN</sub>	Receiver Input Resistance	V <sub>CM</sub> = -7 to 12V	12			KΩ
I <sub>CC</sub>	No Load Supply Current (Note 2)	$V_{RE} = 0V \text{ or } V_{CC}$ $V_{DE} = V_{CC}$ $V_{DE} = 0V$		400 300	900 500	μA μA
I <sub>OSD1</sub>	Driver Short-Circuit Current, V <sub>O</sub> =High	$V_O = -7 \text{ to } 12V \text{ (Note 3)}$	35		250	mA
I <sub>OSD2</sub>	Driver Short-Circuit Current, V <sub>O</sub> =Low	$V_O = -7 \text{ to } 12V \text{ (Note 3)}$	35		250	mA
I <sub>OSR</sub>	Receiver Short-Circuit Current	$V_O = 0V \text{ to } V_{CC}$	7		95	mA

Note 1: All currents into device pins are positive; all cuttents out of device pins are negative; all voltages are referenced to device ground unless specified.

Note 2: Supply current specification is valid for loaded transmitters when  $V_{DE} = 0V$ Note 3: Applies to peak current. See typical Operating Characteristics.

#### DRIVER SWITCHING CHARACTERISTICS

( $V_{CC}$  = 5V ±5%,  $T_A$  =  $T_{MIN}$  to  $T_{MAX}$ , unless otherwise specified. Typical values are referred to  $T_A$  = 25°C) (See Note 1)

Symbol	Parameter	Test 0	Conditions	Min.	Тур.	Max.	Unit
t <sub>PLH</sub>	Propagation Delay Input to	$R_{DIFF} = 54\Omega$	$C_{L1} = C_{L2} = 100pF$	10	30	60	ns
t <sub>PHL</sub>	Output	(See Fig. 3 and 5)					
t <sub>SK</sub>	Output Skew to Output	$R_{DIFF} = 54\Omega$	$C_{L1} = C_{L2} = 100pF$		5	10	ns
		(See Fig. 3 and 5)					
t <sub>TLH</sub>	Rise or Fall Time	$R_{DIFF} = 54\Omega$	$C_{L1} = C_{L2} = 100pF$	3	15	40	ns
t <sub>THL</sub>		(See Fig. 3 and 5)					
t <sub>PZH</sub>	Output Enable Time	C <sub>L</sub> = 100pF	S2 = Closed		40	70	ns
		(See Fig. 4 and 6)					
t <sub>PZL</sub>	Output Enable Time	C <sub>L</sub> = 100pF	S1 = Closed		40	70	ns
		(See Fig. 4 and 6)					
t <sub>PLZ</sub>	Output Disable Time	$C_L = 15pF$	S1 = Closed		40	70	ns
		(See Fig. 4 and 6)					
t <sub>PHZ</sub>	Output Disable Time	C <sub>L</sub> = 15pF	S2 = Closed		40	70	ns
		(See Fig. 4 and 6)					

Note 1: All currents into device pins are positive; all cuttents out of device pins are negative; all voltages are referenced to device ground unless specified.

## RECEIVER SWITCHING CHARACTERISTICS

(V<sub>CC</sub> = 5V  $\pm$  5%, T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub> , unless otherwise specified. Typical values are referred to T<sub>A</sub> = 25°C) (See Note 1)

Symbol	Parameter	Test C	Conditions	Min.	Тур.	Max.	Unit
t <sub>PLH</sub>	Propagation Delay Input to Output	$R_{DIFF} = 54\Omega$ (See Fig. 3 and 7)	$C_{L1} = C_{L2} = 100pF$	20	130	210	ns
t <sub>SKD</sub>	Differential Receiver Skew	$R_{DIFF} = 54\Omega$ (See Fig. 3 and 7)	$C_{L1} = C_{L2} = 100pF$		13		ns
t <sub>PZH</sub>	Output Enable Time	C <sub>RL</sub> = 15pF (See Fig. 2 and 8)	S1 = Closed		20	50	ns
t <sub>PZL</sub>	Output Enable Time	C <sub>RL</sub> = 15pF (See Fig. 2 and 8)	S2 = Closed		20	50	ns
t <sub>PLZ</sub>	Output Disable Time	C <sub>RL</sub> = 15pF (See Fig. 2 and 8)	S1 = Closed		20	50	ns
t <sub>PHZ</sub>	Output Disable Time	C <sub>RL</sub> = 15pF (See Fig. 2 and 8)	S2 = Closed		20	50	ns
f <sub>MAX</sub>	Maximum Data Rate			2.5			Mbps

Note 1: All currents into device pins are positive; all cuttents out of device pins are negative; all voltages are referenced to device ground unless specified.

#### **TEST CIRCUITS AND TYPICAL CHARACTERISTICS**

Figure 1 : Driver DC Test Load

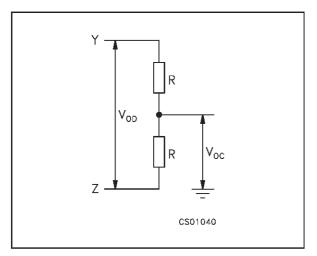


Figure 2: Receiver Timing Test Load

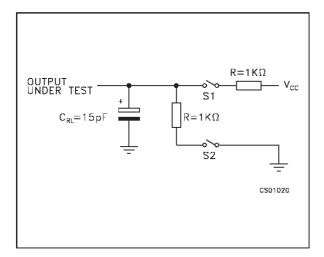


Figure 3 : Drive/Receiver Timing Test Circuit

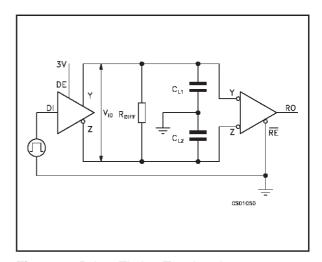


Figure 4 : Driver Timing Test Load

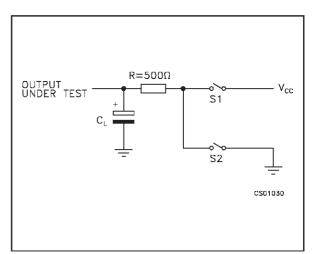


Figure 5 : Driver Propagation Delay

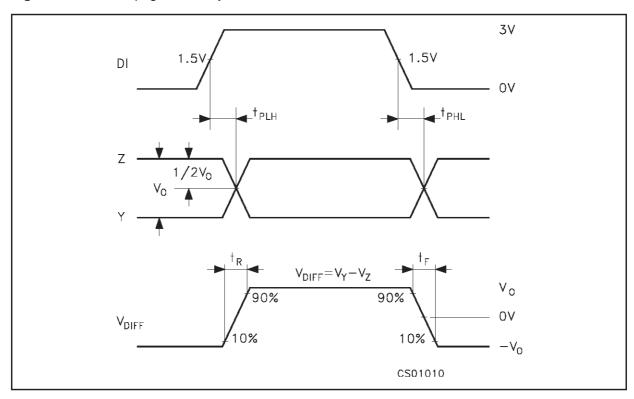


Figure 6: Driver Enable and Disable Time

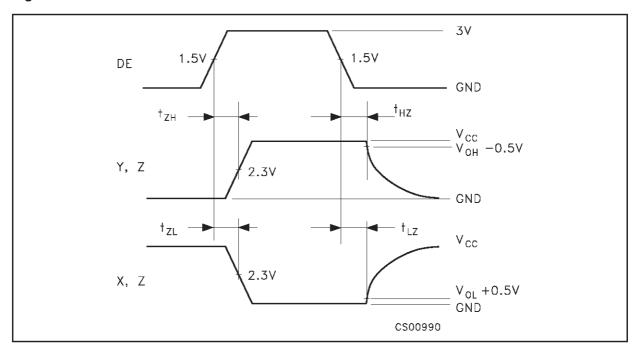


Figure 7: Receiver Propagation Delay

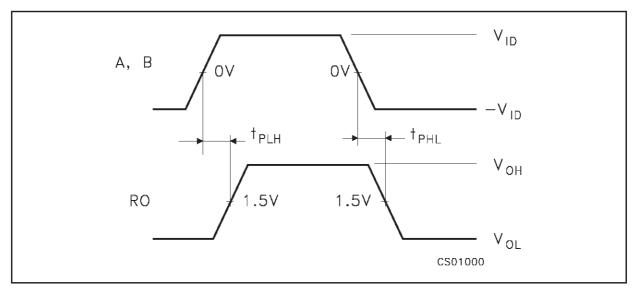
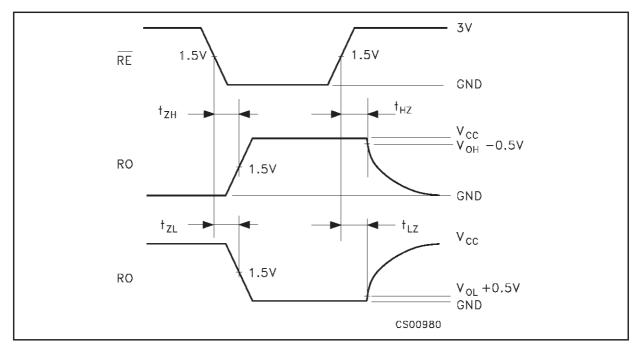
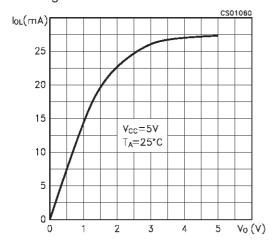


Figure 8: Receiver Enable and Disable Time



**Figure 9 :** Receiver Output Current vs Output Low Voltage



**Figure 10 :** Receiver Output Current vs Output High Voltage

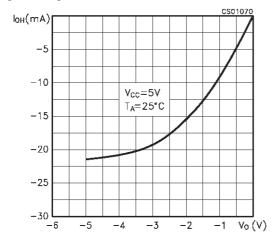
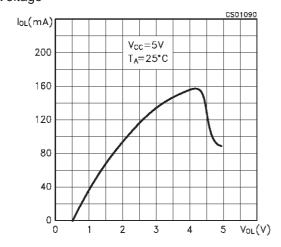


Figure 11 : Driver Output Current vs Output Low Voltage



**Figure 12 :** Driver Output Current vs Output High Voltage

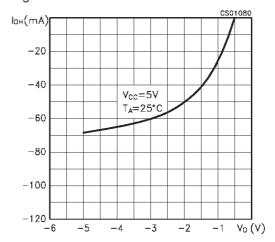
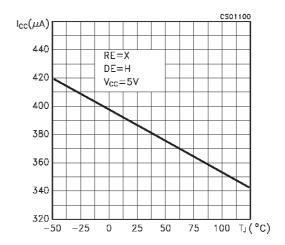


Figure 13 : Supply Current vs Temperature



**Figure 14 :** Receiver High Level Output Voltage vs Temperature

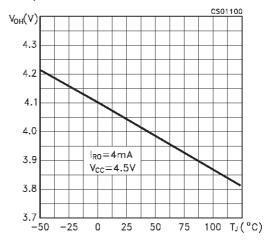
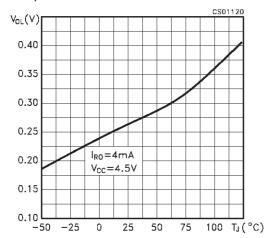
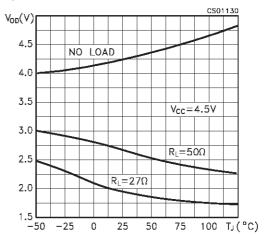


Figure 15 : Receiver Low Level Output Voltage vs Temperature

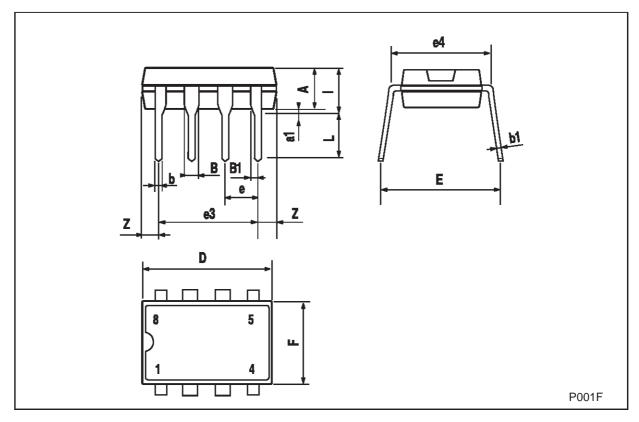


**Figure 16 :** Differential Driver Output Voltage vs Temperature



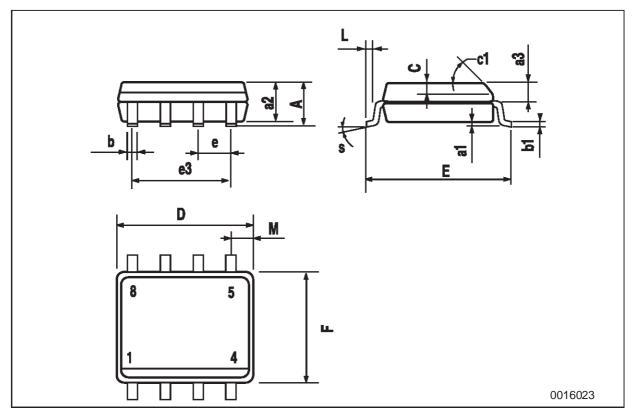
## **Plastic DIP-8 MECHANICAL DATA**

DIM		mm.			inch	
DIM.	MIN.	TYP	MAX.	MIN.	TYP.	MAX.
А		3.3			0.130	
a1	0.7			0.028		
В	1.39		1.65	0.055		0.065
B1	0.91		1.04	0.036		0.041
b		0.5			0.020	
b1	0.38		0.5	0.015		0.020
D			9.8			0.386
Е		8.8			0.346	
е		2.54			0.100	
e3		7.62			0.300	
e4		7.62			0.300	
F			7.1			0.280
I			4.8			0.189
L		3.3			0.130	
Z	0.44		1.6	0.017		0.063



# **SO-8 MECHANICAL DATA**

DIM		mm.			inch			
DIM.	MIN.	TYP	MAX.	MIN.	TYP.	MAX.		
А			1.75			0.068		
a1	0.1		0.25	0.003		0.009		
a2			1.65			0.064		
a3	0.65		0.85	0.025		0.033		
b	0.35		0.48	0.013		0.018		
b1	0.19		0.25	0.007		0.010		
С	0.25		0.5	0.010		0.019		
c1			45°	(typ.)				
D	4.8		5.0	0.189		0.196		
Е	5.8		6.2	0.228		0.244		
е		1.27			0.050			
e3		3.81			0.150			
F	3.8		4.0	0.149		0.157		
L	0.4		1.27	0.015		0.050		
М			0.6			0.023		
S			8° (	max.)		•		



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577