

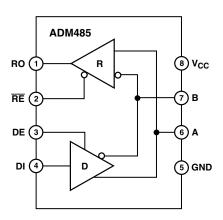
5 V Low Power EIA RS-485 Transceiver

ADM485

FEATURES Meets EIA RS-485 Standard 5 Mbps Data Rate Single 5 V Supply -7 V to +12 V Bus Common-Mode Range High Speed, Low Power BiCMOS **Thermal Shutdown Protection Short Circuit Protection Driver Propagation Delay: 10 ns** Receiver Propagation Delay: 15 ns **High Z Outputs with Power Off** Superior Upgrade for LTC485

APPLICATIONS Low Power RS-485 Systems **DTE-DCE Interface Packet Switching Local Area Networks Data Concentration Data Multiplexers** Integrated Services Digital Network (ISDN)

FUNCTIONAL BLOCK DIAGRAM 8-Lead



GENERAL DESCRIPTION

The ADM485 is a differential line transceiver suitable for high speed bidirectional data communication on multipoint bus transmission lines. It is designed for balanced data transmission and complies with both EIA Standards RS-485 and RS-422. The part contains a differential line driver and a differential line receiver. Both the driver and the receiver may be enabled independently. When disabled, the outputs are three-stated.

The ADM485 operates from a single 5 V power supply. Excessive power dissipation caused by bus contention or by output shorting is prevented by a thermal shutdown circuit. This feature forces the driver output into a high impedance state if during fault conditions a significant temperature increase is detected in the internal driver circuitry.

Up to 32 transceivers may be connected simultaneously on a bus, but only one driver should be enabled at any time. It is important, therefore, that the remaining disabled drivers do not load the bus. To ensure this, the ADM485 driver features high output impedance when disabled and also when powered down.

This minimizes the loading effect when the transceiver is not being utilized. The high impedance driver output is maintained over the entire common-mode voltage range from -7 V to +12 V.

The receiver contains a fail-safe feature that results in a logic high output state if the inputs are unconnected (floating).

The ADM485 is fabricated on BiCMOS, an advanced mixed technology process combining low power CMOS with fast switching bipolar technology. All inputs and outputs contain protection against ESD; all driver outputs feature high source and sink current capability. An epitaxial layer is used to guard against latch-up.

The ADM485 features extremely fast switching speeds. Minimal driver propagation delays permit transmission at data rates up to 5 Mbps while low skew minimizes EMI interference.

The part is fully specified over the commercial and industrial temperature range and is available in DIP, SOIC, and small footprint MSOP packages.

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$\begin{tabular}{ll} ADM485--SPECIFICATIONS & (V_{CC}=5~V~\pm~5\%.~All~specifications~T_{MIN}~to~T_{MAX},~unless~otherwise~noted.) \end{tabular}$

Parameter	Min	Typ	Max	Unit	Test Conditions/Comments
DRIVER					
Differential Output Voltage, V _{OD}			5.0	V	R = ∞, Test Circuit 1
	2.0		5.0	V	$V_{CC} = 5 \text{ V}, R = 50 \Omega \text{ (RS-422)}, \text{ Test Circuit 1}$
	1.5		5.0	V	$R = 27 \Omega$ (RS-485), Test Circuit 1
V_{OD3}	1.5		5.0	V	$V_{TST} = -7 \text{ V to } +12 \text{ V}$, Test Circuit 2
$\Delta V_{OD} $ for Complementary Output States			0.2	V	$R = 27 \Omega$ or 50 Ω, Test Circuit 1
Common-Mode Output Voltage V _{OC}			3	V	$R = 27 \Omega$ or 50 Ω, Test Circuit 1
$\Delta V_{OD} $ for Complementary Output States			0.2	V	$R = 27 \Omega \text{ or } 50 \Omega$
Output Short Circuit Current (V _{OUT} = High)	35		250	mA	$-7 \text{ V} \le \text{V}_{\text{O}} \le +12 \text{ V}$
Output Short Circuit Current (V _{OUT} = Low)	35		250	mA	$-7 \text{ V} \le \text{V}_{\text{O}} \le +12 \text{ V}$
CMOS Input Logic Threshold Low, V _{INL}			0.8	V	
CMOS Input Logic Threshold High, V _{INH}	2.0			V	
Logic Input Current (DE, DI)			± 1.0	μΑ	
RECEIVER					
Differential Input Threshold Voltage, V _{TH}	-0.2		+0.2	V	$-7 \text{ V} \le \text{V}_{\text{CM}} \le +12 \text{ V}$
Input Voltage Hysteresis, ΔV_{TH}		70		mV	$V_{CM} = 0 V$
Input Resistance	12			kΩ	$-7 \text{ V} \le \text{V}_{\text{CM}} \le +12 \text{ V}$
Input Current (A, B)			1	mA	$V_{IN} = 12 \text{ V}$
-			-0.8	mA	$V_{IN} = -7 \text{ V}$
CMOS Input Logic Threshold Low, V _{INL}			0.8	V	
CMOS Input Logic Threshold High, V _{INH}	2.0			V	
Logic Enable Input Current (RE)			± 1	μΑ	
CMOS Output Voltage Low, V _{OL}			0.4	V	$I_{OUT} = 4.0 \text{ mA}$
CMOS Output Voltage High, V _{OH}	4.0			V	$I_{OUT} = -4.0 \text{ mA}$
Short Circuit Output Current	7		85	mA	$V_{OUT} = GND \text{ or } V_{CC}$
Three-State Output Leakage Current			± 1.0	μΑ	$0.4 \text{ V} \le \text{V}_{\text{OUT}} \le 2.4 \text{ V}$
POWER SUPPLY CURRENT					
I _{CC} (Outputs Enabled)		1.0	2.2	mA	Digital Inputs = GND or V_{CC}
I _{CC} (Outputs Disabled)		0.6	1	mA	Digital Inputs = GND or V_{CC}

Specifications subject to change without notice.

TIMING SPECIFICATIONS ($V_{CC}=5~V~\pm~5\%$. All specifications T_{MIN} to T_{MAX} , unless otherwise noted.)

Parameter	Min	Тур	Max	Unit	Test Conditions/Comments
DRIVER					
Propagation Delay Input to Output t _{PLH} , t _{PHL}	2	10	18	ns	$R_{LDIFF} = 54 \Omega$, $C_{L1} = C_{L2} = 100 \text{ pF}$, Test Circuit 3
Driver O/P to $\overline{\text{O/P}}$ t _{SKEW}		1	5	ns	$R_{LDIFF} = 54 \Omega$, $C_{L1} = C_{L2} = 100 \text{ pF}$, Test Circuit 3*
Driver Rise/Fall Time t _R , t _F		8	15	ns	$R_{LDIFF} = 54 \Omega$, $C_{L1} = C_{L2} = 100 \text{ pF}$, Test Circuit 3
Driver Enable to Output Valid		10	25	ns	$R_L = 110 \Omega$, $C_L = 50 pF$, Test Circuit 4
Driver Disable Timing		10	25	ns	$R_L = 110 \Omega$, $C_L = 50 pF$, Test Circuit 4
Matched Enable Switching		0	2	ns	$R_L = 110 \Omega$, $C_L = 50 pF$, Test Circuit 4
$ t_{AZH}-t_{BZL} , t_{BZH}-t_{AZL} $					
Matched Disable Switching		0	2	ns	$R_L = 110 \Omega$, $C_L = 50 pF$, Test Circuit 4
$ t_{AHZ}-t_{BLZ} , t_{BHZ}-t_{ALZ} $					
RECEIVER					
Propagation Delay Input to Output tpl.H, tpHI	8	15	40	ns	C _L = 15 pF, Test Circuit 5
Skew $ t_{PLH} - t_{PHL} $			7	ns	C _L = 15 pF, Test Circuit 5
Receiver Enable t _{EN1}		5	25	ns	$C_L = 15 \text{ pF}, R_L = 1 \text{ k}\Omega, \text{ Test Circuit 6}$
Receiver Disable t _{EN2}		5	25	ns	$C_L = 15 \text{ pF}, R_L = 1 \text{ k}\Omega, \text{ Test Circuit 6}$
Tx Pulsewidth Distortion		1		ns	
Rx Pulsewidth Distortion		1		ns	

^{*}Guaranteed by characterization.

Specifications subject to change without notice.

-2-REV. C

ABSOLUTE MAXIMUM RATINGS*

$(T_A =$	25°C,	unless	otherwise	noted.)
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(1 _A = 25 C, unless otherwise noted.)
V_{CC} –0.3 V to +6 V
Inputs
Driver Input (DI) -0.3 V to V_{CC} + 0.3 V
Control Inputs (DE, $\overline{\text{RE}}$)0.3 V to V _{CC} + 0.3 V
Receiver Inputs (A, B)9 V to +14 V
Outputs
Driver Outputs (A, B)9 V to +14 V
Receiver Output -0.5 V to V_{CC} + 0.5 V
Power Dissipation 8-Lead MSOP 900 mW
θ_{JA} , Thermal Impedance 206°C/W
Power Dissipation 8-Lead DIP 500 mW
θ_{JA} , Thermal Impedance
Power Dissipation 8-Lead SOIC 450 mW
θ_{JA} , Thermal Impedance
Operating Temperature Range
Commercial (J Version) 0°C to 70°C
Industrial (A Version)40°C to +85°C
Storage Temperature Range65°C to +150°C
Lead Temperature (Soldering, 10 sec) 300°C
Vapor Phase (60 sec)
Infrared (15 sec)

^{*}Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those listed in the operational sections of this specification is not implied. Exposure to absolute maximum ratings for extended periods of time may affect device reliability.

Table I. Transmitting

INPUTS		OUTPUTS		
DE	DI	В	A	
1	1	0	1	
1	0	1	0	
0	X	Z	Z	

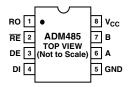
Table II. Receiving

RE	INPUTS A-B	OUTPUT RO
0	≥ +0.2 V	1
0	≤-0.2 V	0
0	Inputs Open	1
1	X	Z

PIN FUNCTION DESCRIPTIONS

Pin	Mnemonic	Function
1	RO	Receiver Output. When enabled if A > B by 200 mV, then RO = High. If A < B by 200 mV, then RO = Low.
2	RE	Receiver Output Enable. A low level enables the receiver output, RO. A high level places it in a high impedance state.
3	DE	Driver Output Enable. A high level enables the driver differential outputs, A and B. A low level places it in a high impedance state.
4	DI	Driver Input. When the driver is enabled, a logic low on DI forces A low and B high while a logic high on DI forces A high and B low.
5	GND	Ground Connection, 0 V
6	A	Noninverting Receiver Input A/Driver Output A
7	В	Inverting Receiver Input B/Driver Output B
8	V_{CC}	Power Supply, 5 V ± 5%

PIN CONFIGURATION



ORDERING GUIDE

Model	Temperature Range	Package Option	Branding Information
ADM485JN	0°C to 70°C	N-8	
ADM485JR	0°C to 70°C	R-8	
ADM485AN	−40°C to +85°C	N-8	
ADM485AR	−40°C to +85°C	R-8	
ADM485ARM	−40°C to +85°C	RM-8	M41

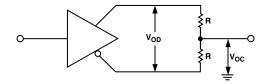
CAUTION _

ESD (electrostatic discharge) sensitive device. Electrostatic charges as high as 4000 V readily accumulate on the human body and test equipment and can discharge without detection. Although the ADM485 features proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.

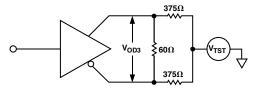


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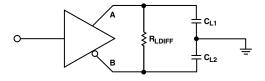
Test Circuits



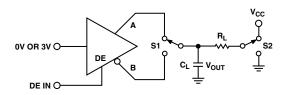
Test Circuit 1. Driver Voltage Measurement



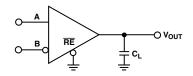
Test Circuit 2. Driver Voltage Measurement



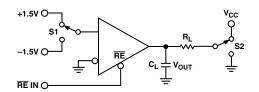
Test Circuit 3. Driver Propagation Delay



Test Circuit 4. Driver Enable/Disable



Test Circuit 5. Receiver Propagation Delay



Test Circuit 6. Receiver Enable/Disable

Switching Characteristics

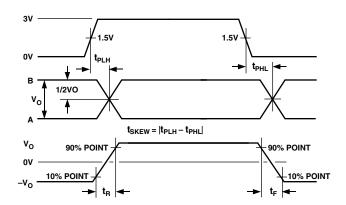


Figure 1. Driver Propagation Delay, Rise/Fall Timing

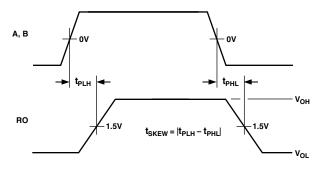


Figure 3. Receiver Propagation Delay

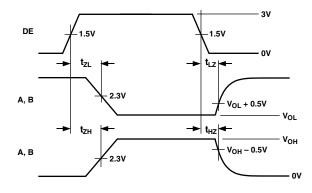


Figure 2. Driver Enable/Disable Timing

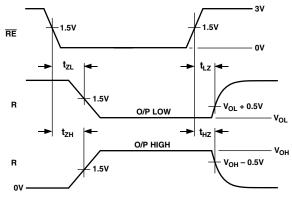
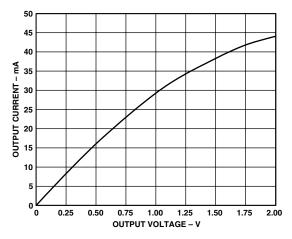
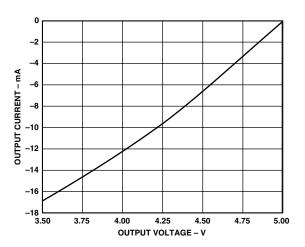


Figure 4. Receiver Enable/Disable Timing

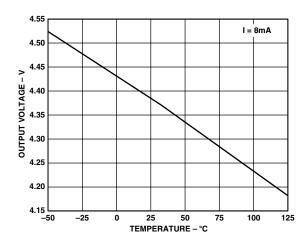
Typical Performance Characteristics—ADM485



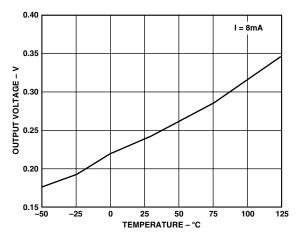
TPC 1. Output Current vs. Receiver Output Low Voltage



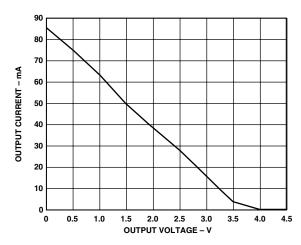
TPC 2. Output Current vs. Receiver Output High Voltage



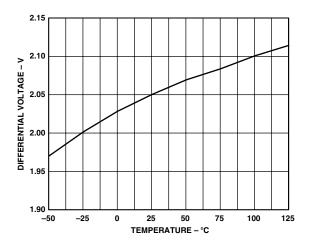
TPC 3. Receiver Output High Voltage vs. Temperature



TPC 4. Receiver Output Low Voltage vs. Temperature

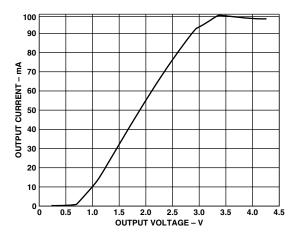


TPC 5. Output Current vs. Driver Differential Output Voltage

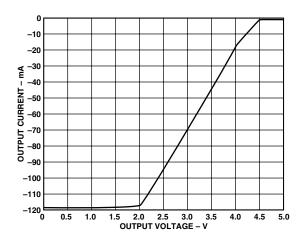


TPC 6. Driver Differential Output Voltage vs. Temperature, $R_{\rm L}=26.8~\Omega$

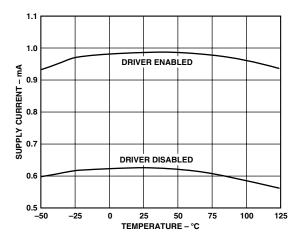
REV. C –5–



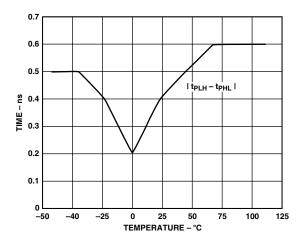
TPC 7. Output Current vs. Driver Output Low Voltage



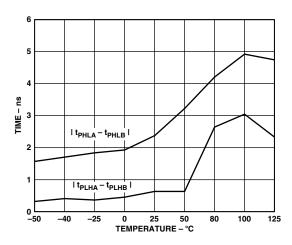
TPC 8. Output Current vs. Driver Output High Voltage



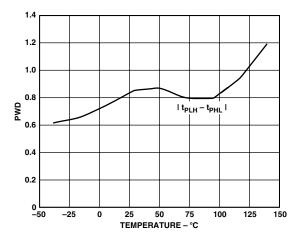
TPC 9. Supply Current vs. Temperature



TPC 10. Rx Skew vs. Temperature

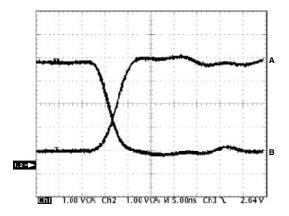


TPC 11. Tx Skew vs. Temperature

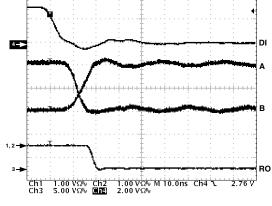


TPC 12. Tx Pulsewidth Distortion

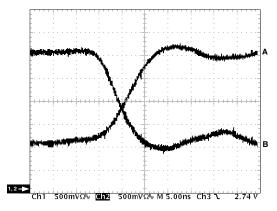
6 REV. C



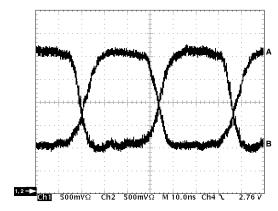
TPC 13. Unloaded Driver Differential Outputs



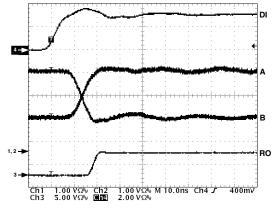
TPC 16. Driver/Receiver Propagation Delays High to Low



TPC 14. Loaded Driver Differential Outputs



TPC 17. Driver Output at 30 Mbps



TPC 15. Driver/Receiver Propagation Delays Low to High

REV. C -7-

APPLICATION INFORMATION

Differential Data Transmission

Differential data transmission is used to reliably transmit data at high rates over long distances and through noisy environments. Differential transmission nullifies the effects of ground shifts and noise signals that appear as common-mode voltages on the line. There are two main standards approved by the Electronics Industries Association (EIA) that specify the electrical characteristics of transceivers used in differential data transmission.

The RS-422 standard specifies data rates up to 10 MBaud and line lengths up to 4000 ft. A single driver can drive a transmission line with up to 10 receivers.

In order to cater for true multipoint communications, the RS-485 standard was defined. This standard meets or exceeds all the requirements of RS-422 but also allows for up to 32 drivers and 32 receivers to be connected to a single bus. An extended common-mode range of –7 V to +12 V is defined. The most significant difference between RS-422 and RS-485 is the fact that the drivers may be disabled, thereby allowing more than one (32 in fact) to be connected to a single line. Only one driver should be enabled at a time, but the RS-485 standard contains additional specifications to guarantee device safety in the event of line contention.

Table III. Comparison of RS-422 and RS-485 Interface Standards

Specification	RS-422	RS-485
Transmission Type Maximum Cable Length Minimum Driver Output Voltage Driver Load Impedance Receiver Input Resistance Receiver Input Sensitivity	Differential 4000 ft. $\pm 2 \text{ V}$ 100 Ω 4 k Ω min $\pm 200 \text{ mV}$	Differential 4000 ft. $\pm 1.5 \text{ V}$ 54 Ω 12 k Ω min $\pm 200 \text{ mV}$
Receiver Input Voltage Range	-7 V to +7 V	-7 V to +12 V
No. of Drivers/Receivers Per Line	1/10	32/32

Cable and Data Rate

The transmission line of choice for RS-485 communications is a twisted pair. Twisted pair cable tends to cancel common-mode noise and also causes cancellation of the magnetic fields generated by the current flowing through each wire, thereby reducing the effective inductance of the pair.

The ADM485 is designed for bidirectional data communications on multipoint transmission lines. A typical application showing a multipoint transmission network is illustrated in Figure 5. An RS-485 transmission line can have as many as 32 transceivers

on the bus. Only one driver can transmit at a particular time, but multiple receivers may be enabled simultaneously.

As with any transmission line, it is important that reflections be minimized. This can be achieved by terminating the extreme ends of the line using resistors equal to the characteristic impedance of the line. Stub lengths of the main line should also be kept as short as possible. A properly terminated transmission line appears purely resistive to the driver.

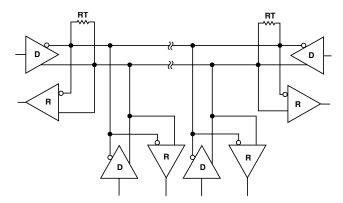


Figure 5. Typical RS-485 Network

Thermal Shutdown

The ADM485 contains thermal shutdown circuitry that protects the part from excessive power dissipation during fault conditions. Shorting the driver outputs to a low impedance source can result in high driver currents. The thermal sensing circuitry detects the increase in die temperature and disables the driver outputs. The thermal sensing circuitry is designed to disable the driver outputs when a die temperature of 150°C is reached. As the device cools, the drivers are re-enabled at 140°C.

Propagation Delay

The ADM485 features very low propagation delay, ensuring maximum baud rate operation. The driver is well balanced, ensuring distortion free transmission.

Another important specification is a measure of the skew between the complementary outputs. Excessive skew impairs the noise immunity of the system and increases the amount of electromagnetic interference (EMI).

Receiver Open-Circuit Fail-Safe

The receiver input includes a fail-safe feature that guarantees a logic high on the receiver when the inputs are open circuit or floating.

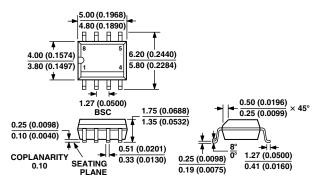
8 REV. C

OUTLINE DIMENSIONS

8-Lead Standard Small Outline Package [SOIC]

(R-8)

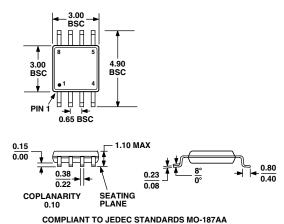
Dimensions shown in millimeters and (inches)



COMPLIANT TO JEDEC STANDARDS MS-012AA
CONTROLLING DIMENSIONS ARE IN MILLIMETERS; INCH DIMENSIONS
(IN PARENTHESES) ARE ROUNDED-OFF MILLIMETER EQUIVALENTS FOR
REFERENCE ONLY AND ARE NOT APPROPRIATE FOR USE IN DESIGN

8-Lead microSOIC Package [MSOP] (RM-8)

Dimensions shown in millimeters

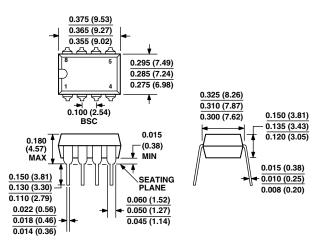


REV. C –9–

OUTLINE DIMENSIONS

8-Lead Plastic Dual-in-Line Package [PDIP] (N-8)

Dimensions shown in inches and (millimeters)



COMPLIANT TO JEDEC STANDARDS MO-095AA
CONTROLLING DIMENSIONS ARE IN INCHES; MILLIMETER DIMENSIONS
(IN PARENTHESES) ARE ROUNDED-OFF INCH EQUIVALENTS FOR
REFERENCE ONLY AND ARE NOT APPROPRIATE FOR USE IN DESIGN

REV. C -10-

Revision History

Location	Page
1/03—Data Sheet changed from REV. B to REV. C.	
Change to SPECIFICATIONS	
Change to ORDERING GUIDE	
12/02—Data Sheet changed from REV. A to REV. B.	
Deleted Q-8 Package	Universal
Edits to FEATURES	
Edits to GENERAL DESCRIPTION	
Edits, additions to SPECIFICATIONS	
Edits, additions to ABSOLUTE MAXIMUM RATINGS	
Additions to ORDERING GUIDE	
TPCs updated and reformatted	
Addition of 8-Lead MSOP Package	
Update to OUTLINE DIMENSIONS	

REV. C -11-