

ST75C176

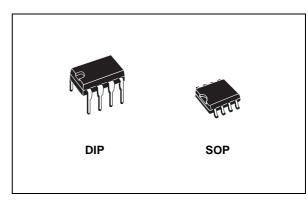
LOW POWER RS-485/RS-422 TRANSCEIVER

- LOW QUIESCENT CURRENT: 300µA
- DESIGNED FOR RS-485 INTERFACE APPLICATIONS
- -7V TO 12V COMMON MODE INPUT VOLTAGE RANGE
- DRIVER MAINTAINS HIGH IMPEDANCE IN 3-STATE OR WITH THE POWER OFF
- 70mV TYPICAL INPUT HYSTERESIS
- 30ns PROPAGATION DELAYS, 5ns SKEW
- OPERATE FROM A SINGLE 5V SUPPLY
- CURRENT LIMITING AND THERMAL SHUTDOWN FOR DRIVER OVERLOAD PROTECTION
- ALLOWS UP TO 32 TRANSCEIVERS ON THE BUS
- BIC MOS TECHNOLOGY

DESCRIPTION

The ST75C176 is al low power transceiver for RS-485 and RS-422 communication. Each part contains one driver and one receiver.

This transceiver draw $300\mu A$ (typ.) of supply current when unloaded or fully loaded with disabled drivers.



It operates from a single 5V supply.

Driver is short-circuit current limited and is protected against excessive power dissipation by thermal shutdown circuitry that placed the driver outputs into a high-impedance state. The receiver input has a fail safe feature that guarantees a logic-high output if the input is open circuit.

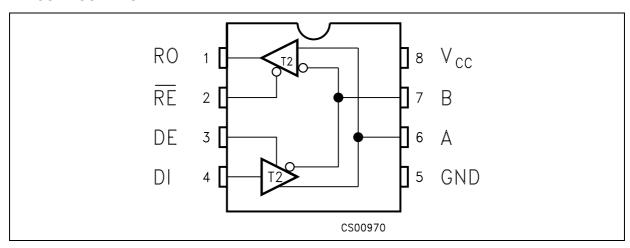
The ST75C176 is designed for bi-directional data communications on multipoint bus transmission line (half-duplex applications).

ORDERING CODES

Туре	Temperature Range	Package	Comments
ST75C176CN	0 to 70 °C	DIP-8	50parts per tube / 40tube per box
ST75C176BN	-40 to 85 °C	DIP-8	50parts per tube / 40tube per box
ST75C176CD	0 to 70 °C	SO-8 (Tube)	100parts per tube / 20tube per box
ST75C176BD	-40 to 85 °C	SO-8 (Tube)	100parts per tube / 20tube per box
ST75C176CDR	0 to 70 °C	SO-8 (Tape & Reel)	2500 parts per reel
ST75C176BDR	-40 to 85 °C	SO-8 (Tape & Reel)	2500 parts per reel

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PIN CONFIGURATION



PIN DESCRIPTION

PIN N°	SYMBOL	NAME AND FUNCTION
1	RO	Receiver Output
2	RE	Receiver Output Enable
3	DE	Driver Output Enable
4	DI	Driver Input
5	GND	Ground
6	A	Non-inverting Receiver Input and Non-inverting Driver Output
7	В	Inverting Receiver Input and Inverting Driver Output
8	V _{CC}	Supply Voltage

TRUTH TABLE (DRIVER)

INPUTS			OUTI	PUTS
RE	DE	В	Α	
Х	Н	Н	L	Н
Х	Н	L	Н	L
X	Ĺ	Χ	Z	Z

X= Don't Care; Z=High Impedance

TRUTH TABLE (RECEIVER)

	INPUTS				
RE	DE	A-B	RO		
L	L	≥ +0.2V	Н		
L	L	≤ - 0.2V	L		
L	L	INPUTS OPEN	Н		
Н	L	Х	Z		

X= Don't Care; Z=High Impedance

ABSOLUTE MAXIMUM RATINGS

Symbol	Parameter	Value	Unit
V _{CC}	Supply Voltage	12	V
V _I	Control Input Voltage (RE, DE)	-0.5 to (V _{CC} + 0.5)	V
V _{DI}	Driver Input Voltage (DI)	-0.5 to (V _{CC} + 0.5)	V
V_{DO}	Driver Output Voltage (A, B)	± 14	V
V _{RI}	Receiver Input Voltage (A, B)	± 14	V
V _{RO}	Receiver Output Voltage (RO)	-0.5 to (V _{CC} + 0.5)	V

Absolute Maximum Ratings are those values beyond which damage to the device may occur. Functional operation under these condition is not implied.

DC ELECTRICAL CHARACTERISTICS

 $(V_{CC} = 5V \pm 5\%, \, T_A = T_{MIN} \ \, \text{to} \, \, T_{MAX} \, , \, \text{unless otherwise specified.} \, \, \text{Typical values are referred to} \, \, T_A = 25^{\circ}\text{C})$ (See Note 1)

Symbol	Parameter	Test Conditions	Min.	Тур.	Max.	Unit
V _{OD1}	Differential Driver Output (No Load)				5	V
V _{OD2}	Differential Driver Output (With Load)	$R_L = 27\Omega \text{ (RS-485) (See Fig. 1)}$ $R_L = 50\Omega \text{ (RS-422) (See Fig. 1)}$	1.5		5 5	V V
ΔV _{OD}	Change in Magnitude of Driver Differential Output Voltage for Complementary Output States	$R_L = 27\Omega$ or 50Ω (See Fig. 1)			0.2	V
V _{OC}	Driver Common-Mode Output Voltage	$R_L = 27\Omega \text{ or } 50\Omega \text{ (See Fig. 1)}$			3	V
ΔV _{OC}	Change in Magnitude of Driver Common-Mode Output Voltage for Complementary Output States	R_L = 27Ω or 50Ω (See Fig. 1)			0.2	V
V_{IH}	Input High Voltage	RE, DE, DI	2.0			V
V_{IL}	Input Low Voltage	RE, DE, DI			0.8	V
I _{IN1}	Input Current	RE, DE, DI			± 2	μΑ
I _{IN2}	Input Current (A, B)	$V_{CM} = 0V \text{ or } 5.25V$ $V_{DE} = 0V$ $V_{IN} = 12V$ $V_{IN} = -7V$			1 -0.8	mA mA
V _{TH}	Receiver Differential Threshold Voltage	V _{CM} = -7 to 12V	-0.2		0.2	V
ΔV_{TH}	Receiver Input Hysteresis	$V_{CM} = 0V$		70		mV
V _{OH}	Receiver Output High Voltage	$I_O = -4mA$ $V_{ID} = 200mV$	3.5			V
V _{OL}	Receiver Output Low Voltage	$I_O = 4mA$ $V_{ID} = -200mV$			0.4	V
I _{OZR}	3-State (High Impedance) Output Current at Receiver	$V_0 = 0.4 \text{ to } 2.4 \text{V}$			± 1	μΑ
R _{IN}	Receiver Input Resistance	$V_{CM} = -7 \text{ to } 12V$	12			KΩ
Icc	No Load Supply Current (Note 2)	$V_{RE} = 0V \text{ or } V_{CC}$ $V_{DE} = V_{CC}$ $V_{DE} = 0V$		400 300	900 500	μA μA
I _{OSD1}	Driver Short-Circuit Current, V _O =High	V _O = -7 to 12V (Note 3)	35		250	mA
I _{OSD2}	Driver Short-Circuit Current, V _O =Low	$V_O = -7$ to 12V (Note 3)	35		250	mA
I _{OSR}	Receiver Short-Circuit Current	$V_O = 0V$ to V_{CC}	7		95	mA

Note 1: All currents into device pins are positive; all cuttents out of device pins are negative; all voltages are referenced to device ground unless specified.

Note 2: Supply current specification is valid for loaded transmitters when $V_{DE} = 0V$ Note 3: Applies to peak current. See typical Operating Characteristics.

DRIVER SWITCHING CHARACTERISTICS

(V_{CC} = 5V ±5%, T_A = T_{MIN} to T_{MAX} , unless otherwise specified. Typical values are referred to T_A = 25°C) (See Note 1)

Symbol	Parameter	Test C	Conditions	Min.	Тур.	Max.	Unit
t _{PLH}	Propagation Delay Input to	$R_{DIFF} = 54\Omega$	$C_{L1} = C_{L2} = 100pF$	10	30	60	ns
t _{PHL}	Output	(See Fig. 3 and 5)					
t _{SK}	Output Skew to Output	$R_{DIFF} = 54\Omega$	$C_{L1} = C_{L2} = 100pF$		5	10	ns
		(See Fig. 3 and 5)					
t _{TLH}	Rise or Fall Time	$R_{DIFF} = 54\Omega$	$C_{L1} = C_{L2} = 100pF$	3	15	40	ns
t _{THL}		(See Fig. 3 and 5)					
t _{PZH}	Output Enable Time	C _L = 100pF	S2 = Closed		40	70	ns
		(See Fig. 4 and 6)					
t _{PZL}	Output Enable Time	C _L = 100pF	S1 = Closed		40	70	ns
		(See Fig. 4 and 6)					
t _{PLZ}	Output Disable Time	C _L = 15pF	S1 = Closed		40	70	ns
		(See Fig. 4 and 6)					
t _{PHZ}	Output Disable Time	C _L = 15pF	S2 = Closed		40	70	ns
		(See Fig. 4 and 6)					

Note 1: All currents into device pins are positive; all cuttents out of device pins are negative; all voltages are referenced to device ground unless specified.

RECEIVER SWITCHING CHARACTERISTICS

(V_{CC} = 5V \pm 5%, T_A = T_{MIN} to T_{MAX} , unless otherwise specified. Typical values are referred to T_A = 25°C) (See Note 1)

Symbol	Parameter	Test 0	Conditions	Min.	Тур.	Max.	Unit
t _{PLH}	Propagation Delay Input to Output	$R_{DIFF} = 54\Omega$ (See Fig. 3 and 7)	$C_{L1} = C_{L2} = 100pF$	20	130	210	ns
t _{SKD}	Differential Receiver Skew	$R_{DIFF} = 54\Omega$ (See Fig. 3 and 7)	$C_{L1} = C_{L2} = 100pF$		13		ns
t _{PZH}	Output Enable Time	C _{RL} = 15pF (See Fig. 2 and 8)	S1 = Closed		20	50	ns
t _{PZL}	Output Enable Time	C _{RL} = 15pF (See Fig. 2 and 8)	S2 = Closed		20	50	ns
t _{PLZ}	Output Disable Time	C _{RL} = 15pF (See Fig. 2 and 8)	S1 = Closed		20	50	ns
t _{PHZ}	Output Disable Time	C _{RL} = 15pF (See Fig. 2 and 8)	S2 = Closed		20	50	ns
f _{MAX}	Maximum Data Rate			2.5			Mbps

Note 1: All currents into device pins are positive; all cuttents out of device pins are negative; all voltages are referenced to device ground unless specified.

TEST CIRCUITS AND TYPICAL CHARACTERISTICS

Figure 1 : Driver DC Test Load

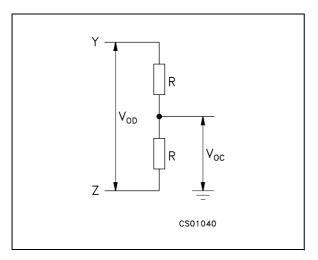


Figure 2 : Receiver Timing Test Load

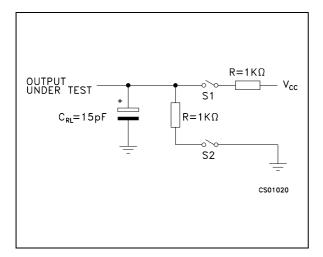


Figure 3 : Drive/Receiver Timing Test Circuit

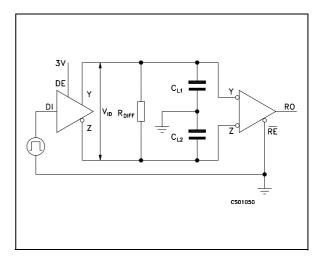


Figure 4 : Driver Timing Test Load

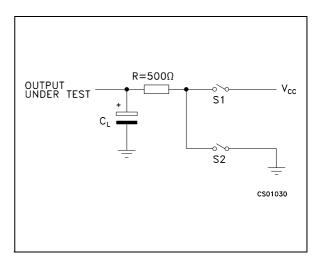


Figure 5 : Driver Propagation Delay

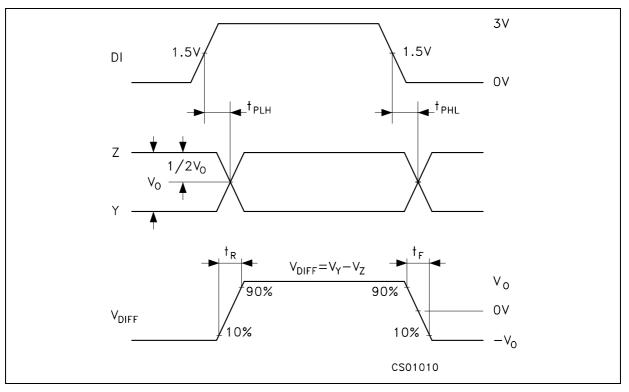


Figure 6: Driver Enable and Disable Time

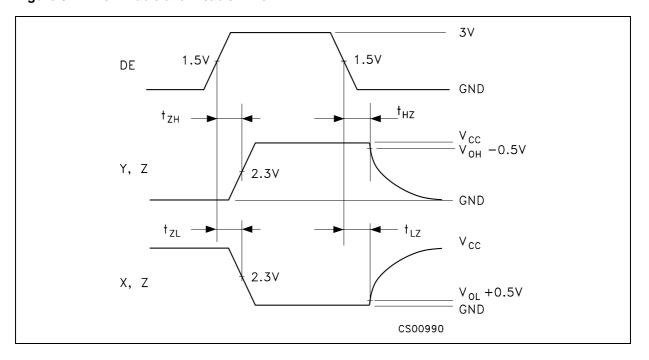


Figure 7: Receiver Propagation Delay

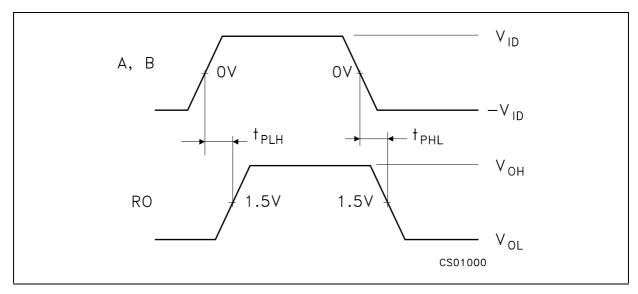


Figure 8: Receiver Enable and Disable Time

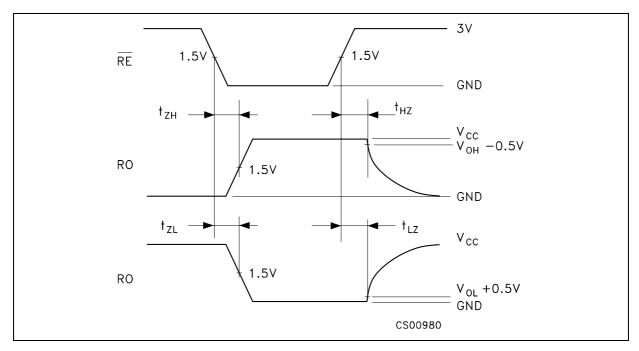


Figure 9 : Receiver Output Current vs Output Low Voltage

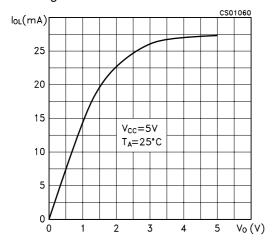


Figure 10 : Receiver Output Current vs Output High Voltage

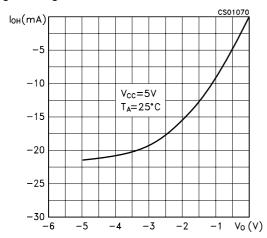


Figure 11 : Driver Output Current vs Output Low Voltage

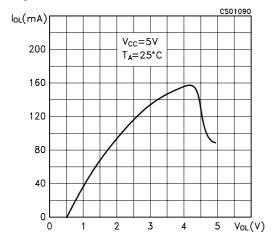


Figure 12 : Driver Output Current vs Output High Voltage

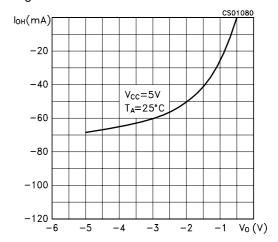


Figure 13 : Supply Current vs Temperature

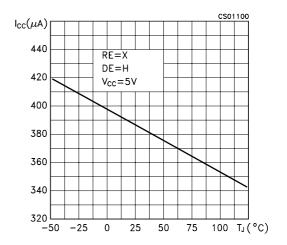


Figure 14 : Receiver High Level Output Voltage vs Temperature

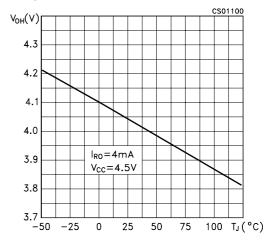


Figure 15 : Receiver Low Level Output Voltage vs Temperature

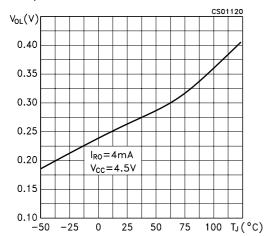
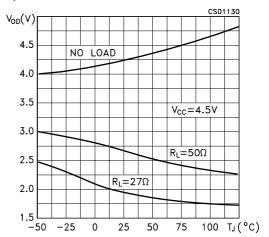
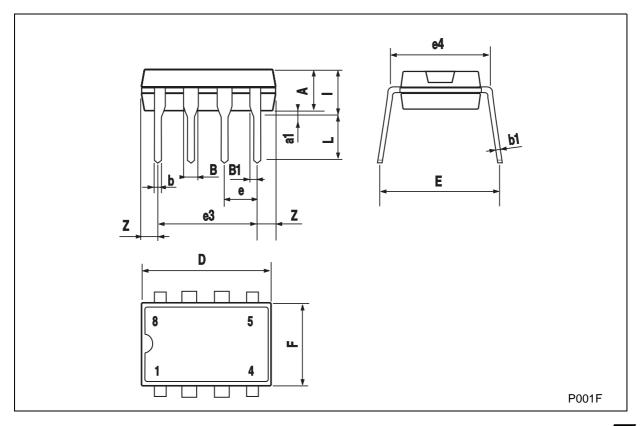


Figure 16: Differential Driver Output Voltage vs Temperature



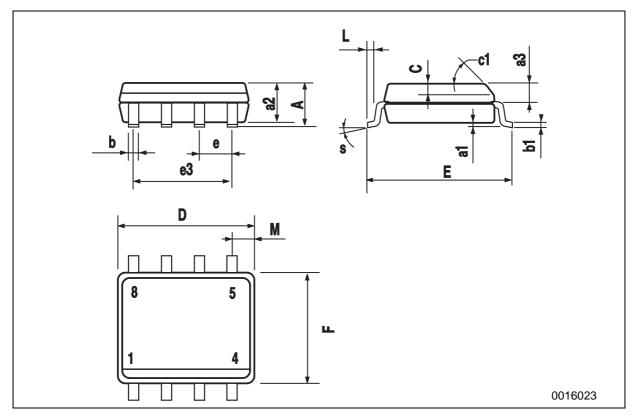
Plastic DIP-8 MECHANICAL DATA

DIM		mm.			inch			
DIM.	MIN.	TYP	MAX.	MIN.	TYP.	MAX.		
А		3.3			0.130			
a1	0.7			0.028				
В	1.39		1.65	0.055		0.065		
B1	0.91		1.04	0.036		0.041		
b		0.5			0.020			
b1	0.38		0.5	0.015		0.020		
D			9.8			0.386		
E		8.8			0.346			
е		2.54			0.100			
e3		7.62			0.300			
e4		7.62			0.300			
F			7.1			0.280		
1			4.8			0.189		
L		3.3			0.130			
Z	0.44		1.6	0.017		0.063		



SO-8 MECHANICAL DATA

DIM		mm.		inch			
DIM.	MIN.	TYP	MAX.	MIN.	TYP.	MAX.	
Α			1.75			0.068	
a1	0.1		0.25	0.003		0.009	
a2			1.65			0.064	
a3	0.65		0.85	0.025		0.033	
b	0.35		0.48	0.013		0.018	
b1	0.19		0.25	0.007		0.010	
С	0.25		0.5	0.010		0.019	
c1			45°	(typ.)		•	
D	4.8		5.0	0.189		0.196	
E	5.8		6.2	0.228		0.244	
е		1.27			0.050		
e3		3.81			0.150		
F	3.8		4.0	0.149		0.157	
L	0.4		1.27	0.015		0.050	
М			0.6			0.023	
S		•	8° (ı	max.)	•	•	



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