# ON Semiconductor's D2 Series Transistors for Fluorescent Converters 

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## INTRODUCTION

Switching bipolar transistors are very popular in the fluorescent ballast field where they provide cheap designs. Nevertheless, the use of bipolar transistors is not straightforward; they are based on minority carrier operation, making switching simulation difficult and inaccurate. Designing fluorescent converters with standard bipolar transistors requires a certain amount of skill.

Due to the inductive storage time (tsi) variations and the optimization of fall time, the switching losses and the case

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## APPLICATION NOTE

temperature are probably the most critical issues the designer has to deal with.
The aim of the D 2 series is to drastically simplify the design of electronic ballasts for fluorescent tubes. This is possible due to the integration of two extra devices (D2): a freewheeling diode; and an anti-saturation network.
This application note presents the interest of the D2 structure and how to utilize this new series to solve the critical issues that the designer must deal with.


Figure 1. Standard Bipolar Transistor, Two Emitter Fingers Cross Section

## Standard Bipolar Transistors Structure

During the saturation phase, the base and collector regions are filled with carriers that significantly reduce the resistivity of these areas.

This phenomenon has two consequences:

1. During turn off, the base resistance is either shorted to the emitter or connected to a negative voltage, so as the internal base voltage is still positive, the minority carriers are extracted from the base area (see Figures 21 and 22).

This phase takes time because the base resistivity depends on the carrier density of each part of the base area. The faster the carriers located near the base contact are extracted, the faster the resistivity increases near the base contact and the slower the carriers located under the emitter fingers will be extracted (Figure 2).
During this phase, the base current (named $\mathrm{I}_{\mathrm{B} 2}$ ) is negative, but $\mathrm{V}_{\text {CE }}$ is still $\mathrm{V}_{\text {CEsat }}$ and $\mathrm{I}_{\mathrm{C}}$ is still flowing. This phase corresponds to the storage time (tsi).


Figure 2. Poor Minority Carriers Extraction
When no charge remains trapped within the base, $\mathrm{I}_{\mathrm{B} 2}$ decreases to zero and $\mathrm{I}_{\mathrm{C}}$ goes to zero as well. This is the fall-time phase (see Figure 3 and Reference 3).


Figure 3. tsi and tfi Definition
2. The drop of resistivity of the base and collector areas allows very low collector to emitter voltage, even if the current density is high ( $\mathrm{V}_{\mathrm{CEsat}}$ ) (see Figure 4).


Figure 4. Minority Carriers Distribution During Saturation Condition

The low resistivity of the emitter, base, and active collector areas, combined with their small depth, make the resistance of these areas very low compared to the substrate.
This modulation mechanism of the resistivity explains why bipolar on losses are smaller than those of MOSFET for a given die size.

## D2 Series Structure

Figure 5 shows the cross section of a D2 device. The main difference between D2 series and other transistors having built-in freewheeling diodes is the way the freewheeling diode is designed.

Instead of adding the diode in a corner of the die, the D2 devices have the diode distributed across the active area of the transistor. This protected geometry gives an extra lateral PNP and unique advantages.


Figure 5. D2 Transistor Simplified Cross Section

## Freewheeling Diode

An important point would be to measure the dynamic parameters of this diode. Unfortunately, the measurement of the $t_{\mathrm{rr}}$ and $\mathrm{Q}_{\mathrm{rr}}$ is impossible because it is not possible to isolate the distributed diode from the transistor structure.

However, we can compare $\mathrm{I}_{\mathrm{C}}$ waveforms coming from the application between BUL44 (standard switching transistor using external freewheeling diode), against BUL44D2.

Figure 6 shows the typical waveform of the BUL44 collector current associated with 1N4937, Figure 7 with

MUR160, and Figure 8 depicts BUL44D2 $\mathrm{I}_{\mathrm{C}}$ curves. As we can see, the distributed diode behavior is close by the MUR160 one from a $t_{\mathrm{rr}}$ point of view.

One must point out that there is no advantage to connect an extra freewheeling diode across a D2 device. This external diode sets a different $\mathrm{Q}_{\mathrm{rr}}$ than that of the internal one, and the PNP behavior is highly modified, implying an increase of power losses and heat dissipation within the switch.

Figure 7. BUL44 and MUR160


Figure 6. BUL44 and 1N4937


Figure 8. BUL44D2

## Anti-Saturation Network

The anti-saturation network is built around the extra PNP connected, as shown in Figure 9. The effective $\mathrm{I}_{\mathrm{B}}$ current of the main transistor is controlled by the feedback provided through the PNP and the $\mathrm{V}_{\text {CEsat }}$ sense of the NPN structure


Figure 9. D2 Equivalent Schematic

Like the Baker clamp (Figure 10), this network either allows proportional drive or avoids hard saturation. The base current of the power transistor is limited when its $\mathrm{V}_{\mathrm{CE}}$ voltage becomes too low. In case of a Baker clamp, the minimum $\mathrm{V}_{\mathrm{CE}}$ is about two diode drops, as given by equation [1].

$$
V_{C E s a t}=V_{B E}+V_{D 1}+V_{D 2}-V_{D 4}
$$

 compensate for the drop coming from D4.

Figure 10. Baker Clamp Schematic

The anti-saturation network built in the D2 devices gives the same advantages as the Baker clamp, but without the drawback of a high $\mathrm{V}_{\text {CEsat. }}$. Figures 11 and 12 show two curves comparing dynamic $\mathrm{V}_{\text {CEsat }}$ observed in case of a BUL44D2, and the Baker clamp topology built around a BUL44 and 1N4937.


Figure 11. BUL44D2 Dynamic VCEdyn


Figure 12. BUL44/Baker Clamp VCEdyn

Note: Due to the test jig depicted in Figure 13, we must subtract 600 mV (calibrated) from the values observed coming from the diode drop.

This gives a net $\mathrm{V}_{\text {CEsat }}$ of 507 mV for BUL44D2, compared to 1.92 V for the Baker clamp topology. Since R1 is small, this circuit has a small parasitic time constant R1Cp.


Since R1 is Small, this Schematic Allows a Small Parasitic Time Constant R1Cp.
Figure 13. Dynamic $\mathrm{V}_{\text {CEsat }}$ Test Jig

## Critical Application Requirements

The purpose of this paragraph is not to establish an exhaustive list of the switches technical requirements, but to point out the most critical ones (refer to AN1543/D "Electronic Lamp Ballast," where switch selection is described).

## Inductive Storage Time (tsi) Dispersion

The inductive storage time corresponds to the time required to extract the charges stored within the base, the collector load being inductive.

Since the tsi is a part of the converter half period, tsi variations can be pernicious to the lifetime of the tube. Due to the inductive load, frequency variations mean power dissipation variations within the tube. Figure 14 shows the consequences of tsi variations on the power dissipated.


Figure 14. Ptube versus $\Delta$ (tsi)

We can observe the extremely tight tsi dispersion of D2 devices compared to standard ones. The specification
guarantees the tsi dispersion at $\pm 150 \mathrm{~ns}$ (whatever be the temperature within the specified range), and the output power follows the same dispersion.
Figure 15 shows the $\mathrm{t}_{\text {off }}$ variation of the BUL45D2 versus the temperature between $-40^{\circ} \mathrm{C}$ and $+125^{\circ} \mathrm{C}$. Leaving aside the tolerances coming from the measurements, the $\mathrm{t}_{\text {off }}$ variation follows a straight line and, due to the tight dispersion of this parameter, is absolutely predictable.


Figure 15. BUL45D2 $t_{\text {off }}$ Variation versus Temperature

Manufacturing standard fluorescent converters using bipolar transistors requires to guaranty an $\mathrm{h}_{\mathrm{FE}}$ window to correlate a tsi window.

In the case of D 2 devices, $\mathrm{h}_{\mathrm{FE}}$ windows no longer make sense. Since the power transistor and the PNP are diffused on the same die, $\mathrm{h}_{\text {FE }}$ variations are equivalent for both transistors. $\mathrm{PNP}_{\mathrm{FE}}$ variation tends to compensate the NPN, making tsi nearly constant when $\mathrm{h}_{\mathrm{FE}}$ varies.

## Fall Time and Power Losses

Power losses are an important criterion since they are responsible for the operating case temperature which can be approximated using equation [2]:

$$
\begin{equation*}
\mathrm{T}_{\mathrm{C}}-\mathrm{T}_{\mathrm{a}}=\mathrm{P}_{1} \times \text { RthJA } \tag{eq.2}
\end{equation*}
$$

where $T_{c}=$ Case temperature
$\mathrm{T}_{\mathrm{a}}=$ Ambient temperature
$\mathrm{P}_{1} \quad=$ Power losses within the switch
Rth $h_{\mathrm{JA}}=$ Thermal resistance between Junction to Ambient
(Assuming Rth ${ }_{\mathrm{JA}} \gg \mathrm{Rth}_{\mathrm{JC}}$ ).
Since for reliability reasons the junction temperature is limited at $150^{\circ} \mathrm{C}$ max, the lower the losses, the higher the ambient temperature can be. Following the usual analysis, power losses can be split in four different parts corresponding to the four phases of a switching sequence (Figure 16).


Figure 16. Switching Sequence

1. Turn off losses: The minority carriers trapped into the base and the collector areas, during the on phase, are responsible of fall time. This produces losses only during switch off as the $\mathrm{dV}_{\mathrm{CE}} / \mathrm{dt}$ is high due to inductive switching. Figure 17 shows BUL45D2 and BUL45 tfi under the same bias condition.
2. Off losses are negligible due to the low value of the leakage current.
3. Turn on losses are negligible as well because $\mathrm{V}_{\mathrm{CE}}$ drops to $\mathrm{V}_{\mathrm{CEsat}}$ before $\mathrm{I}_{\mathrm{C}}$ increases.
4. On losses: They are characterized by the product $\mathrm{V}_{\text {CEsat }} \times \mathrm{I}_{\mathrm{C}}$.

During the saturation phase, the base and the collector areas are filled with minority carriers. This reduces the resistivity of the silicon and provides low losses (Figure 4).


Figure 17. BUL45D2 tfi: 95 ns, BUL45 tfi: 150 ns

Due to the D2 design, the power dissipated within the switch is no longer related to the switching phase, but comes from the on phase ${ }^{(1)}$. This is extremely important from a design safety point of view.
During the turn off phase, the transistor is reverse biased ( $\mathrm{I}_{\mathrm{B}}$ is negative, $\mathrm{V}_{\mathrm{CE}}$ and $\mathrm{I}_{\mathrm{C}}$ positive) and has to sustain a moving $\mathrm{I}_{\mathrm{C}} / \mathrm{V}_{\mathrm{CE}}$ operating point. The switch can be destroyed in few microseconds if this point goes out of the Reverse Bias Safe Operating Area as shown in Figure 18 (see AN873/D and AN875/D). Power losses produced during the on phase are safer because they follow thermal laws.

MJE18004D2: RBSOA


Figure 18. Typical RBSOA Curve versus Different Reverse Bias Voltages Applied on the Base

[^0]
## D2 in Fluorescent Application

Another important advantage of this network consists in the drastic simplification of the calculation of the drive and so the development time of the designer. Usually designers have to adapt the oscillation transformer output to the transistor.

The base drive conditions set up the behavior of the transistor as follows:
$\mathrm{I}_{\mathrm{B} 1}$ peak must be high enough to guaranty low $\mathrm{V}_{\mathrm{CEsat}}$
$\mathrm{I}_{\mathrm{B} 1}$ negative going slope must be optimized to adjust the tsi and the frequency
$\mathrm{I}_{\mathrm{B} 2}$ shall be adjusted to minimize turn off losses.
We must point out that it is difficult to achieve the accurate control of the negative-going slope of the base current in a cheap way. The use of the D2 device is simpler as it is less sensible to the $\mathrm{I}_{\mathrm{B} 1}$ to $\mathrm{I}_{\mathrm{B} 2}$ transition, and it accommodates sharp edges and high $\mathrm{I}_{\mathrm{B} 2}$ level. The same principle allows proportional drive.

One of the interests of the Baker clamp is the proportional drive that consists in the possibility to drive either one or two tubes or more, keeping the bias network of the transistor constant.

By connecting several tubes to a single converter, the $\mathrm{I}_{\mathrm{C}}$ current varies proportionally to the number of tubes. This means $I_{B}$ current must be able to follow this variation according to the transistor transfer curve.

This is not possible due to the nonlinear response of the saturable core of the oscillation transformer.

The use of D2 devices is a way to overcome this nonlinearity.

## How to Get the Best Benefits Out of the D2 Series

We demonstrated that the D2 series works fine within a wide range of biases. Most of the time designers need transistors operating at a high ambient temperature. (Due to the housing, compact fluorescent ambient temperature can reach $125^{\circ} \mathrm{C}$, the transistors must operate safely. The thermal constraint is more sensitive for DPAK packaged devices.) Generally speaking, the problem consists in pushing further the thermal runaway occurrence.

A possible cause of a thermal runaway is a preswitching off desaturation $\left(\mathrm{V}_{\mathrm{CE}}\right.$ begins to increase at the end of the tsi phase, as $\mathrm{I}_{\mathrm{C}}$ is maximum, before switch off). This phenomenon can occur, mainly with the D2 series, because of
its specific structure. The operating principle of these devices is to never run in hard saturation (Figure 9); this means the among of charges trapped within the base is small. As soon as $I_{B 2}$ extracts a certain amount of charge, $V_{C E}$ tends to increase and the device is desaturated.

Based on the cheapest and the most common drive circuits shown in Figures 19 and 20, the analysis of this specific bipolar transistor operation gives two ways to stabilize the device at high operating temperature, when the $\mathrm{I}_{\mathrm{C}}$ current tends to runaway:

1. Increase the emitter resistance value ( Re ).

As the collector current is high, the drop voltage across the emitter resistance provides a negative feedback to the base of the D2 device. During $\mathrm{I}_{\mathrm{B} 1}$ phases, the net voltage available across the base circuit (out of the secondary of the toroid) is reduced by the feedback voltage.
During $\mathrm{I}_{\mathrm{B} 2}$ phases, the oscillator transformer does not provide any driving voltage and the secondary winding shorts the base resistance to the ground. As the $\mathrm{I}_{\mathrm{C}}$ value is still high, the emitter voltage is positive (Figure 22). This increases $\mathrm{I}_{\mathrm{B} 2}$ (as if a negative voltage were applied across the base), limits any preswitching off desaturation, and significantly improves the thermal behavior of the device.
2. Increase $\mathrm{I}_{\mathrm{B} 1}$ value.

The value of $\mathrm{I}_{\mathrm{B} 1}$ current can be very different without having significant impact on switching parameters, due to the anti-saturation network.

The $\mathrm{h}_{\mathrm{FE}}$ of the built in PNP, like other bipolar transistors, is limited by the level of $\mathrm{I}_{\mathrm{C}}$ current (see typical $\mathrm{h}_{\mathrm{FE}}$ versus $\mathrm{I}_{\mathrm{C}}$ curves) so the extra base current derived via the PNP is limited as well. When $\mathrm{I}_{\mathrm{B} 1}$ is higher than the PNP can handle, its $\mathrm{h}_{\mathrm{FE}}$ drops and the anti-saturation network no longer works. The amount of charges trapped within the power NPN transistor base can be larger and the preswitching desaturation phenomenon disappears.

Both solutions generally imply an adjustment of the toroid turns ratio to adjust the operating frequency.
Designers used to driving standard bipolar transistors know that the negative slope of $\mathrm{I}_{\mathrm{B} 1}$ and the value of $\mathrm{I}_{\mathrm{B} 2}$ are critical to optimize ts, tf , and the switching losses.

Using a D2 device is simple; ts, tf, and switching losses will be optimized as soon as the $\mathrm{I}_{\mathrm{B} 2}$ value is high (this value can be higher than that of $\mathrm{I}_{\mathrm{B} 1}$ ), and the $\mathrm{I}_{\mathrm{B} 2}$ waveform is as square as possible (fast falling edge).


Figure 19.


Figure 20.


Figure 21.


Figure 22.

## CONCLUSION

Standard bipolar transistors are attractive in the lamp ballast field because of their price and performances; nevertheless, designing bipolar transistors requires a certain skill, mainly due to tsi variation from lot to lot.

The new D2 family combines cost advantage and simplifies the design.

The coming of the D2 series allows the saving of PCB space because the freewheeling diode is built in and some drive components can be removed. Due to the specific way the diode is laid out, an anti-saturation network is integrated, providing significant advantages such as extremely tight tsi distribution (typically: $\pm 80 \mathrm{~ns}$ ), inexpensive designs, high operating speed (up to 100 kHz , under accurate biases conditions), lower power dissipation, and proportional drive-enabling variable load.

The D2 family of application specific transistors enables the design of bipolar-based fluorescent converters. They are not only cost effective, but simple and straightforward as well.
SELECTOR GUIDE

| DEVICE TYPE | V $_{\text {CEO }}$ | $\mathrm{V}_{\text {CES }}$ | I $_{\text {Cmax }}$ | PACKAGE |
| :--- | :---: | :---: | :---: | :---: |
| BUD44D2 | 400 V | 700 V | 2 A | DPAK |
| MJD18002D2 | 450 V | 1000 V | 2 A | DPAK |
| BUL44D2 | 400 V | 700 V | 2 A | TO220 |
| BUL45D2 | 400 V | 700 V | 5 A | TO220 |
| MJE18002D2 | 450 V | 1000 V | 2 A | TO220 |
| MJE18004D2 | 450 V | 1000 V | 5 A | TO220 |
| MJE18604D2 | 800 V | 1600 V | 2 A | TO220 |

## References

1. ON Semiconductor, AN873/D: Understanding Power Transistor Dynamic Behavior.
2. ON Semiconductor, AN875/D: Power Transistor Safe Operating Area.
3. ON Semiconductor, AN1543/D: Electronic Lamp Ballast Design.

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[^0]:    (1) It is important to notice this new way to manage the power dissipated within the bipolar transistor allows operating frequencies up to 100 kHz .

