

÷2, ÷4/6 Clock Generation Chip

The MC100LVEL38 is a low skew ÷2, ÷4/6 clock generation chip designed explicitly for low skew clock generation applications. The MC100EL38 is pin and functionally equivalent to the MC100LVEL38 but is specified for operation at the standard 100K ECL voltage supply. The internal dividers are synchronous to each other, therefore, the common output edges are all precisely aligned. The device can be driven by either a differential or single-ended LVECL or, if positive power supplies are used, LVPECL input signal. In addition, by using the V_{BB} output, a sinusoidal source can be AC coupled into the device (see Interfacing section of the ECLinPS™ Data Book DL140/D). If a single-ended input is to be used, the V_{BB} output should be connected to the CLK input and bypassed to ground via a 0.01μF capacitor. The V_{BB} output is designed to act as the switching reference for the input of the LVEL38 under single-ended input conditions, as a result, this pin can only source/sink up to 0.5mA of current.

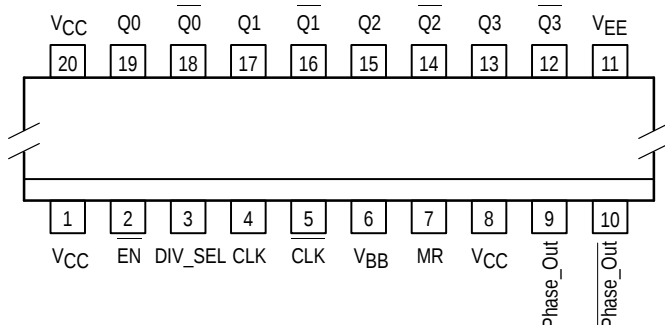
The common enable ($\overline{EN}$) is synchronous so that the internal dividers will only be enabled/disabled when the internal clock is already in the LOW state. This avoids any chance of generating a runt clock pulse on the internal clock when the device is enabled/disabled as can happen with an asynchronous control. An internal runt pulse could lead to losing synchronization between the internal divider stages. The internal enable flip-flop is clocked on the falling edge of the input clock, therefore, all associated specification limits are referenced to the negative edge of the clock input.

The Phase_Out output will go HIGH for one clock cycle whenever the ÷2 and the ÷4/6 outputs are both transitioning from a LOW to a HIGH. This output allows for clock synchronization within the system.

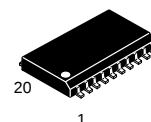
Upon startup, the internal flip-flops will attain a random state; therefore, for systems which utilize multiple LVEL38s, the master reset (MR) input must be asserted to ensure synchronization. For systems which only use one LVEL38, the MR pin need not be exercised as the internal divider design ensures synchronization between the ÷2 and the ÷4/6 outputs of a single device.

- 50ps Output-to-Output Skew
- Synchronous Enable/Disable
- Master Reset for Synchronization
- 75kΩ Internal Input Pulldown Resistors
- >1500V ESD Protection
- Low Voltage V_{EE} Range of -3.0 to -3.8V

Pinout: 20-Lead SOIC (Top View)



MC100LVEL38 MC100EL38



DW SUFFIX
PLASTIC SOIC PACKAGE
CASE 751D-04

PIN DESCRIPTION

PIN	FUNCTION
CLK	Diff Clock Inputs
EN	Sync Enable
MR	Master Reset
V_{BB}	Reference Output
Q0, Q1	Diff ÷2 Outputs
Q2, Q3	Diff ÷4/6 Outputs
DIVSEL	Frequency Select Input
Phase_Out	Phase Sync Signal

FUNCTION TABLE

CLK	$\overline{EN}$	MR	FUNCTION
Z	L	L	Divide
ZZ	H	L	Hold Q0-3
X	X	H	Reset Q0-3

Z = Low-to-High Transition

ZZ = High-to-Low Transition

DIVSEL	Q2, Q3 OUTPUTS
0	Divide by 4
1	Divide by 6



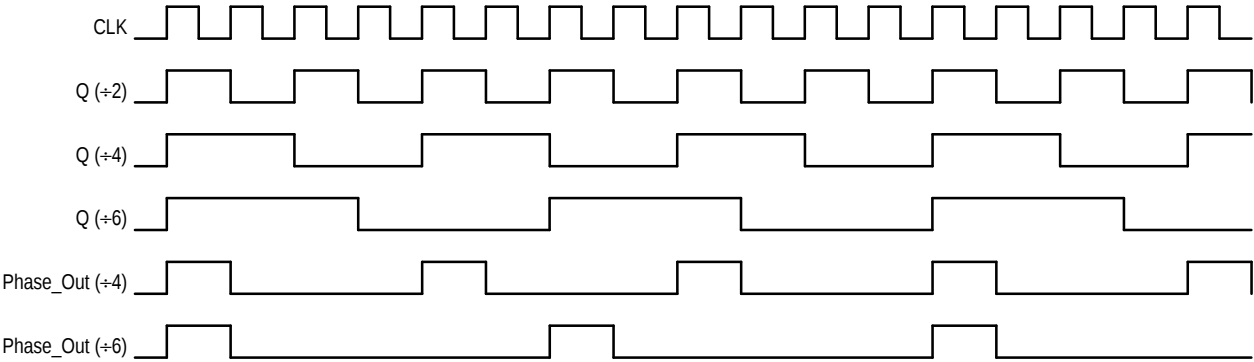
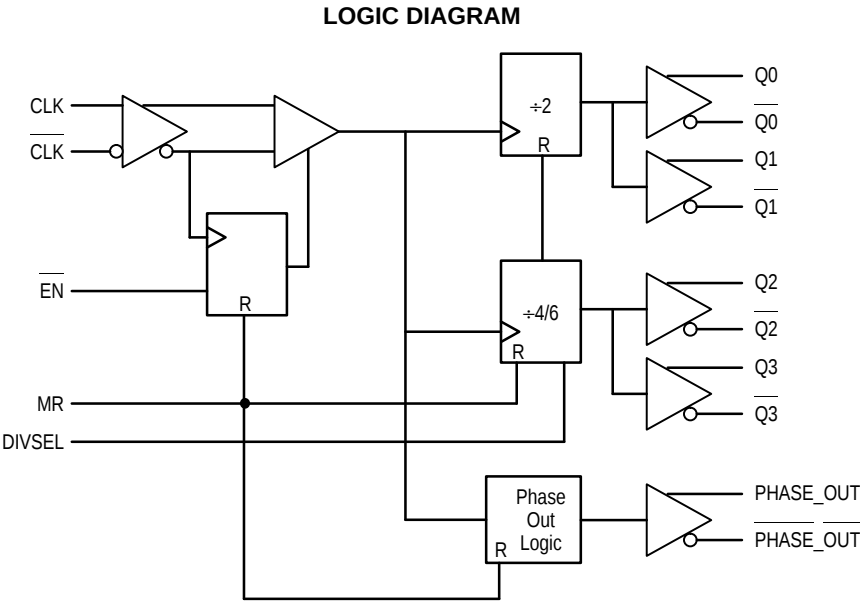


Figure 1. Timing Diagrams

MC100LVEL38**DC CHARACTERISTICS** ($V_{EE} = -3.8V$ to $-3.0V$; $V_{CC} = GND$)

Symbol	Characteristic	-40°C			0°C			25°C			85°C			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
I_{EE}	Power Supply Current		50	60		50	60		50	60		54	65	mA
V_{BB}	Output Reference Voltage	-1.38		-1.26	-1.38		-1.26	-1.38		-1.26	-1.38		-1.26	V
I_{IH}	Input High Current			150			150			150			150	μA

MC100LVEL38**AC CHARACTERISTICS** ($V_{EE} = -3.8V$ to $-3.0V$; $V_{CC} = GND$)

Symbol	Characteristic	-40°C			0°C			25°C			85°C			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
f_{MAX}	Maximum Toggle Frequency	1000			1000			1000			1000			MHz
t_{PLH} t_{PHL}	Propagation Delay to Output CLK → Q (Diff) CLK → Q (S.E.) CLK → Phase_Out (Diff) CLK → Phase_Out (S.E.) MR → Q	760 710 800 750 510		960 1010 1000 1050 810	780 730 820 770 530		980 1030 1020 1070 830	800 750 840 790 540		1000 1050 1040 1090 840	850 800 890 840 570		1050 1100 1090 1140 870	ps
t_{SKEW}	Within-Device Skew ¹ Q ₀ – Q ₃ All			50 75			50 75			50 75			50 75	ps
	Part-to-Part Q ₀ – Q ₃ (Diff) All			200 240			200 240			200 240			200 240	
t_S	Setup Time EN → CLK DIVSEL → CLK		150			150			150			150		ps
t_H	Hold Time CLK → EN CLK → Div_Sel		150 200			150 200			150 200			150 200		ps
V_{PP} ²	Minimum Input Swing CLK	250			250			250			250			mV
V_{CMR} ³	Common Mode Range CLK	-0.55		See ³	-0.55		See ³	-0.55		See ³	-0.55		See ³	V
t_{RR}	Reset Recovery Time			100			100			100			100	ps
t_{PW}	Minimum Pulse Width CLK MR	800 700			800 700			800 700			800 700			ps
t_r, t_f	Output Rise/Fall Times Q (20% – 80%)	280		550	280		550	280		550	280		550	ps

1. Skew is measured between outputs under identical transitions.

2. Minimum input swing for which AC parameters are guaranteed. The device will function reliably with differential inputs down to 100mV.

3. The CMR range is referenced to the most positive side of the differential input signal. Normal operation is obtained if the HIGH level falls within the specified range and the peak-to-peak voltage lies between $V_{PP\ MIN}$ and 1.0V. The lower end of the CMR range is dependent on V_{EE} and is equal to $V_{EE} + 1.65V$.

MC100LVEL38 MC100EL38

MC100EL38

DC CHARACTERISTICS ($V_{EE} = -4.2V$ to -5.46 ; $V_{CC} = GND$)

Symbol	Characteristic	-40°C			0°C			25°C			85°C			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
I_{EE}	Power Supply Current		50	60		50	60		50	60		54	65	mA
V_{BB}	Output Reference Voltage	-1.38		-1.26	-1.38		-1.26	-1.38		-1.26	-1.38		-1.26	V
I_{IH}	Input High Current			150			150			150			150	μA

MC100EL38

AC CHARACTERISTICS ($V_{EE} = -4.2V$ to -5.46 ; $V_{CC} = GND$)

Symbol	Characteristic	-40°C			0°C			25°C			85°C			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
f_{MAX}	Maximum Toggle Frequency	1000			1000			1000			1000			MHz
t_{PLH} t_{PHL}	Propagation Delay CLK → Q (Diff) to Output CLK → Q (S.E.) CLK → Phase_Out (Diff) CLK → Phase_Out (S.E.) MR → Q	760 710 800 750 510		960 1010 1000 1050 810	780 730 820 770 530		980 1030 1020 1070 830	800 750 840 790 540		1000 1050 1040 1090 840	850 800 890 840 570		1050 1100 1090 1140 870	ps
t_{SKEW}	Within-Device Skew ¹ Q ₀ – Q ₃ All			50 75			50 75			50 75			50 75	ps
	Part-to-Part Q ₀ – Q ₃ (Diff) All			200 240			200 240			200 240			200 240	
t_S	Setup Time EN → CLK DIVSEL → CLK		150			150			150			150		ps
t_H	Hold Time CLK → EN CLK → Div_Sel		150 200			150 200			150 200			150 200		ps
V_{PP}^2	Minimum Input Swing CLK	250			250			250			250			mV
V_{CMR}^3	Common Mode Range CLK	-0.55		See ³	-0.55		See ³	-0.55		See ³	-0.55		See ³	V
t_{RR}	Reset Recovery Time			100			100			100			100	ps
t_{PW}	Minimum Pulse Width CLK MR	800 700			800 700			800 700			800 700			ps
t_r, t_f	Output Rise/Fall Times Q (20% – 80%)	280		550	280		550	280		550	280		550	ps

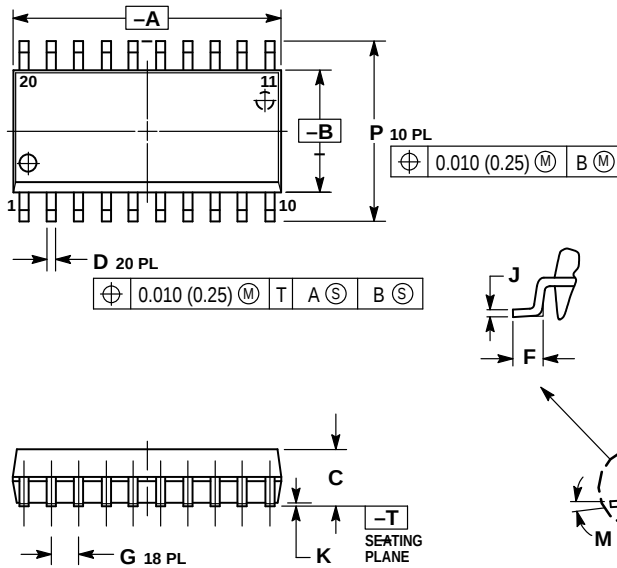
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3. The CMR range is referenced to the most positive side of the differential input signal. Normal operation is obtained if the HIGH level falls within the specified range and the peak-to-peak voltage lies between $V_{PP\ MIN}$ and 1.0V. The lower end of the CMR range is dependent on V_{EE} and is equal to $V_{EE} + 1.65V$.

OUTLINE DIMENSIONS

DW SUFFIX
PLASTIC SOIC PACKAGE
CASE 751D-04
ISSUE E



NOTES:

1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
2. CONTROLLING DIMENSION: MILLIMETER.
3. DIMENSIONS A AND B DO NOT INCLUDE MOLD PROTRUSION.
4. MAXIMUM MOLD PROTRUSION 0.150 (0.006) PER SIDE.
5. DIMENSION D DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.13 (0.005) TOTAL IN EXCESS OF D DIMENSION AT MAXIMUM MATERIAL CONDITION.

DIM	MILLIMETERS		INCHES	
	MIN	MAX	MIN	MAX
A	12.65	12.95	0.499	0.510
B	7.40	7.60	0.292	0.299
C	2.35	2.65	0.093	0.104
D	0.35	0.49	0.014	0.019
F	0.50	0.90	0.020	0.035
G	1.27 BSC		0.050 BSC	
J	0.25	0.32	0.010	0.012
K	0.10	0.25	0.004	0.009
M	0°	7°	0°	7°
P	10.05	10.55	0.395	0.415
R	0.25	0.75	0.010	0.029

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